

EKS36-0KF0B020A

EKS/EKM36

MOTOR FEEDBACK SYSTEMS

SICK
Sensor Intelligence.

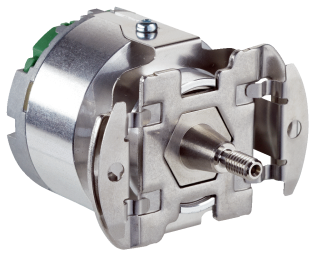


Illustration may differ



Ordering information

Type	Part no.
EKS36-0KF0B020A	1084230

Other models and accessories → www.sick.com/EKS_EKM36

Detailed technical data

Safety-related parameters

MTTF_D (mean time to dangerous failure)	155 years (EN ISO 13849) ¹⁾
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¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 60 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Performance

Position	
Resolution per revolution	20 bit
System accuracy	± 100 "
Signal noise (σ)	± 4 " (See "signal noise" and "attenuation" diagrams)
Number of the absolute ascertainable revolutions	1
Available memory area	8,192 Byte
Measurement step per revolution	1,048,576
Vibration	
Measurement principle	Optical

Interfaces

Type of code for the absolute value	Binary
Code sequence	Increasing, when turning the shaft For clockwise rotation, looking in direction "A" (see dimensional drawing)
Communication interface	HIPERFACE DSL [®]
Initialization time	Max. 500 ms ¹⁾
Measurement external temperature resistance	32 bit value, without prefix (1 Ω) 0 ... 209.600 Ω At -40 °C ... +160 °C: NTC +2K; PTC+3K

¹⁾ From reaching a permitted operating voltage.

Electrical data

Connection type	Male connector, 4-pin
Supply voltage	7 V ... 12 V

¹⁾ Duration of voltage ramp between 0 and 7.0 V.

²⁾ Current rating applies when using interface circuit suggestions as shown in HIPERFACE DSL[®] manual (8017595).

Warm-up time voltage ramp	Max. 180 ms ¹⁾
Recommended supply voltage	8 V
Current consumption	≤ 150 mA (See current consumption diagram) ²⁾
Output frequency for the digital position value	0 kHz ... 75 kHz

¹⁾ Duration of voltage ramp between 0 and 7.0 V.

²⁾ Current rating applies when using interface circuit suggestions as shown in HIPERFACE DSL ® manual (8017595).

Mechanical data

Shaft version	Tapered shaft
Flange type / stator coupling	Stator coupling
Dimensions	See dimensional drawing
Weight	0.1 kg
Moment of inertia of the rotor	4.5 gcm ²
Operating speed	≤ 12,000 min ⁻¹
Angular acceleration	≤ 500,000 rad/s ²
Operating torque	0.2 Ncm
Start up torque	0.3 Ncm
Permissible movement static	± 0.1 mm, ± 0.5 mm radial, axial
Permissible movement dynamic	± 0.05 mm radial ± 0.1 mm axial
Life of ball bearings	3.6 x 10 ⁹ revolutions

Ambient data

Operating temperature range	-20 °C ... +115 °C ¹⁾
Storage temperature range	-40 °C ... +125 °C ²⁾
Relative humidity/condensation	90 %, Condensation not permitted
Resistance to shocks	100 g, 6 ms (according to EN 60068-2-27)
Frequency range of resistance to vibrations	50 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)
EMC	According to EN 61000-6-2, EN 61000-6-4 and IEC 61326-3 ³⁾
Enclosure rating	IP40, with mating connector inserted and closed cover (IEC 60529-1) ⁴⁾

¹⁾ Given typical thermal connection between motor flange and encoder stator coupling. The max. internal sensor temperature may not exceed 125 °C.

²⁾ Without package.

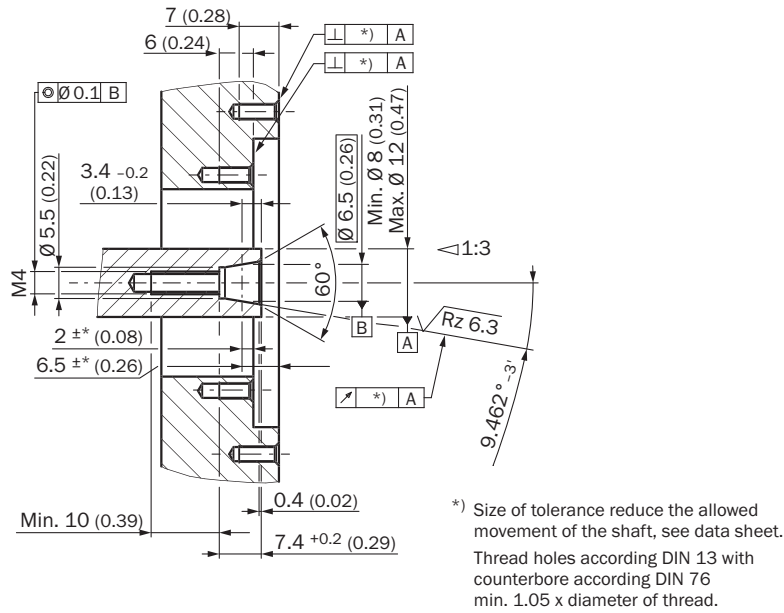
³⁾ The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. The GND-(0 V) connection of the supply voltage is also grounded here. If other shielding concepts are used, users must perform their own tests.

⁴⁾ With mating connector inserted and closed cover.

Classifications

ECLASS 5.0	27270590
ECLASS 5.1.4	27270590
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270590
ECLASS 8.0	27270590

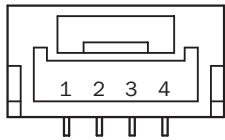
Attachment specifications



- ① Nominal position
- ② The size of the tolerance reduces the permissible wave movement, see data sheet
- ③ Threaded holes in accordance with DIN 13 with recesses in accordance with DIN 76 min. 1.05 x thread diameter

PIN assignment

Supply/communication pin assignment



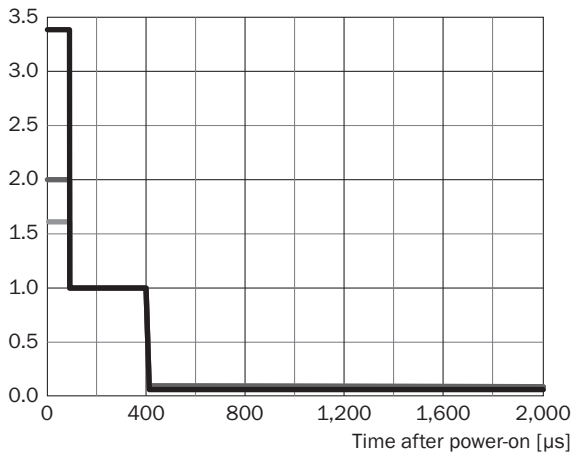
Integrated in motor cable = J, K

PIN	Signal	Explanation
1		Not connected - no function
2	+U _S /DSL+	Supply 7 V ... 12 V
3	GND/DSL-	Ground connection
4	Housing	Screen/Stranded ground wire

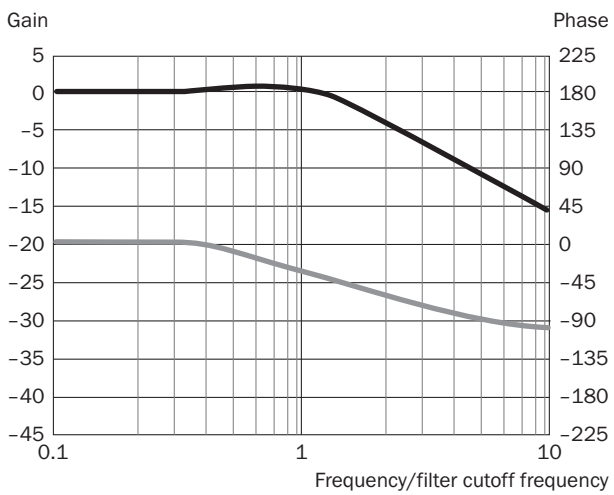
Recommended outer diameter of set of stranded wires: 4 mm +0/-0.3 mm
 Recommended mating connector: JST (GHR-04V-S)

Diagrams

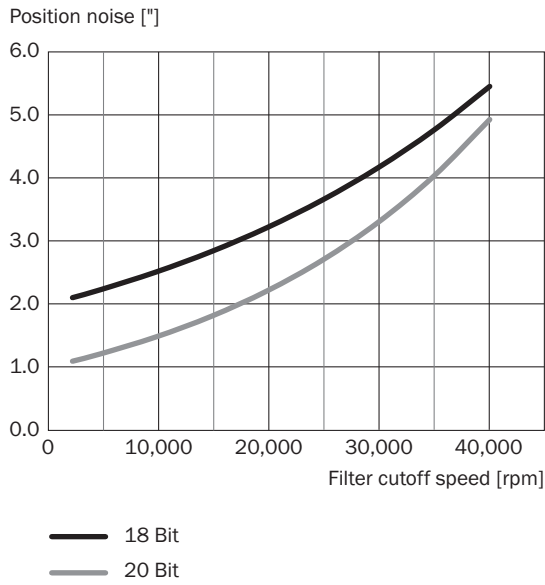
Typ. current consumption [A]



- 7 V
- 8 V
- 12 V



- Gain [dB]
- Phase [°]



Signal noise is measured as 1 standard deviation (σ) of the value distribution. Position filter cutoff speed is set by resource 10Ah, see page 11.

Recommended accessories

Other models and accessories → www.sick.com/EKS_EKM36

	Brief description	Type	Part no.
Other mounting accessories			
	Mounting tools	BEF-MW-EKX36	2060224
Others			
	<ul style="list-style-type: none"> Connection type head A: Female connector, stranded wire, 2-pin, straight Connection type head B: Flying leads Signal type: HIPERFACE DSL[®] Cable: 0.2 m, 2-wire Description: HIPERFACE DSL[®], twisted, unshielded 	DOL-0B02-G0M2XC1	2062083
		DOL-0B02-G0M4XC1	2086286
		DOL-0B03-G0M4XC1	2087314
		DOL-0B02-G0M3XC1	2091818
		DOL-0B02-G0M3AC2	2108944

SICK AT A GLANCE

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We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is “Sensor Intelligence.”

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