EDM35-0VF0A024A

EDS/EDM35

MOTOR FEEDBACK SYSTEMS

SICK
Sensor Intelligence.

Illustration may differ

CE

Ordering information

Type	Part no.
EDM35-0VF0A024A	1106846

Other models and accessories ➔ www.sick.com/EDS_EDM35

Detailed technical data

Safety-related parameters

MTTF$_D$ (mean time to dangerous failure)	150 years (EN ISO 13849) [1]

[1] This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 60°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Performance

Position	
Resolution per revolution	24 bit
System accuracy	± 25 " [1]
Signal noise (σ)	± 1 " [2]
Number of the absolute ascertainable revolutions	4,096
Available memory area	8,192 Byte

[1] In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

[2] Repeatability standard deviation in accordance with DIN 1319-1:1995.

Interfaces

Code sequence	Increasing, when turning the shaft For clockwise rotation, looking in direction "A" (see dimensional drawing)
Communication interface	HIPERFACE DSL®
Initialization time	≤ 500 ms [1]
Measurement external temperature resistance	32-bit value, without prefix (1 Ω) 0 … 209.600 Ω [2]

[1] From reaching a permitted operating voltage.

[2] Without sensor tolerance; at –40 °C … +160 °C: NTC +-2K; PTC+-3K (KTY84-130/PT1000). For additional conversion function of PT1000 to KTY84/130, see technical description.

Electrical data

Connection type	Male connector, 8-pin
Supply voltage	7 V … 12 V
Warm-up time voltage ramp	Max. 180 ms [1]

[1] Duration of voltage ramp between 0 and 7.0 V.

[2] Current rating applies when using interface circuit suggestions as shown in HIPERFACE DSL ® manual (8017595).

Current consumption	≤ 150 mA [2]
Compatible with sHub®	✓

[1] Duration of voltage ramp between 0 and 7.0 V.

[2] Current rating applies when using interface circuit suggestions as shown in HIPERFACE DSL ® manual (8017595).

Mechanical data

Shaft version	Tapered shaft
Dimensions	See dimensional drawing
Weight	≤ 100 g
Moment of inertia of the rotor	5 gcm²
Operating speed	≤ 9,000 min⁻¹
Angular acceleration	≤ 250,000 rad/s²
Start up torque	≤ 0.6 Ncm, +20 °C
Permissible movement static	± 1 mm axial [1]
Permissible movement dynamic	± 0.1 mm radial
Life of ball bearings	50,000 h at 6,000 min⁻¹ (at a flange temperature of 70 °C)

[1] Temperature expansion, mechanical attachment.

Ambient data

Operating temperature range	–40 °C … +115 °C [1]
Storage temperature range	–40 °C … +125 °C, without package
Relative humidity/condensation	90 %, Condensation not permitted
Resistance to shocks	100 g, 6 ms (according to EN 60068-2-27)
Frequency range of resistance to vibrations	50 g, 10 Hz … 2,000 Hz (EN 60068-2-6)
EMC	According to EN 61000-6-2, EN 61000-6-4 and IEC 61326-3 [2]
Enclosure rating	IP40, When cover is closed and mating connector is attached (IEC 60529-1)

[1] Given typical thermal connection between motor flange and encoder stator coupling. The max. internal sensor temperature may not exceed 125 °C.

[2] According to the listed standards, EMC is guaranteed if the motor feedback system with mating connector inserted is connected to the central grounding point of the motor controller via a cable shield. If other shielding concepts are used, users must perform their own tests. Class A device.
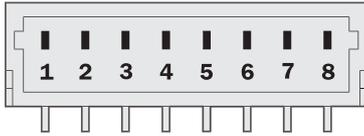
Classifications

ECLASS 5.0	27270590
ECLASS 5.1.4	27270590
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270590
ECLASS 8.0	27270590
ECLASS 8.1	27270590
ECLASS 9.0	27270590
ECLASS 10.0	27273805
ECLASS 11.0	27273901
ECLASS 12.0	27273901
ETIM 5.0	EC001486

ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

① Bearing of the encoder shaft
② Torx 15 cylinder screw
③ Measuring point for vibrations
④ Measuring point for operating temperature

Attachment specifications

① Permanently
② Dynamic
③ Bearing of the drive shaft

PIN assignment

Supply/Communication pin assignment

V connection type

PIN	Signal	Explanation
1	+U$_S$	Supply
2	GND	Ground connection
3	DSL-	DSL negative
4	DSL+	DSL positive
5	RxD+	Receiver data positive
6	RxD-	Receiver data negative
7	TxD-	Sender data negative
8	TxD+	Sender data positive
Recommended mating connector: JST (GHR-08V-S)		

Diagrams

Typical inrush current (A)

- 7 V Us
- 8 V Us
- 12 V Us
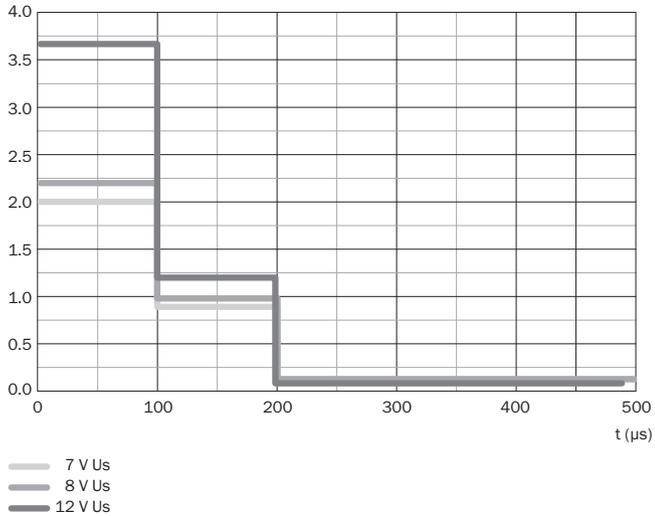
Recommended accessories

Other models and accessories ➜ www.sick.com/EDS_EDM35

Brief description	Type	Part no.
Spare parts		
EDM35 cover set, 10 pcs	BEF-CAP-EDM-010	2139997
EDM35 cover set, 40 pcs	BEF-CAP-EDM-040	2139999

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SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is "Sensor Intelligence."

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